

Delphion

RESEARCH
INTEGRATED IAM
SERVICES
INSIDE DEL

[Home](#)
[About](#)
[Contact](#)

[My Account](#) | [Products](#) | [News](#) | [Events](#)

[Search: Quick/Number](#) [Boolean](#) [All](#)

## The Delphion Integrated View

Buy Now: [PDF](#) | [More choices...](#)

Tools: Add to Work File: [Create new](#)

View: [INPADOC](#) | Jump to: [Top](#) Go to: [Derwent...](#)

**Title:** JP8184436A2: POSITION MEASURING EQUIPMENT AND CAMERA INFORMATION RECORDING FUNCTION

**Country:** JP Japan

**Kind:** A

**Inventor:** MOCHIZUKI YOSHINORI;  
KAWAI MASATADA;

**Assignee:** KONICA CORP  
[News, Profiles, Stocks and More about this company](#)

**Published / Filed:** July 16, 1996 / Dec. 28, 1994

**Application Number:** JP1994000328966

**IPC Code:** G01C 15/00; G03B 17/24;

**Priority Number:** Dec. 28, 1994 JP1994000328966

**Abstract:** **Purpose:** To locate an object remote from a GPS receiver by correcting the positional information at a point to be measured based on the outputs from various sensors thereby locating the object.

**Constitution:** A distance measuring section 1 measures the distance from a measuring point to an object and a GPS receiver 2 detects the position at the measuring point. An orientation sensor 3 detects the orientation of a measuring apparatus when it is directed toward the object as angle from the north and an inclination sensor 4 detects the angle of elevation of the measuring apparatus when it is directed toward the object. When a measuring button 9 is pushed, the equipment is actuated to start measurement through the measuring section 1, the receiver 2 and the sensors 3, 4. When the distance to the object is measured, a laser beam is transmitted from the measuring section 1 to the object and the time elapsed before receiving a reflected laser beam is measured thus determining the distance. Subsequently, a correction amount of the distance is determined, and the position of the object is determined at a control section 5.

COPYRIGHT: (C)1996,JPO

**Family:** [Show 8 known family members](#)

**Other Abstract Info:** DERABS G96-379873 DERG96-379873



[Nominate](#)

[this for the Gallery...](#)

Camera  
GPS  
distance  
orientation  
inclination

BEST AVAILABLE COPY